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EXPECTATIONS AND THE FORWARD EXCHANGE RATE

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Expectations and the Forward Exchange Rate

ABSTRACT

This paper provides an empirical examination of the hypothesis that the forward exchange rate provides an "optimal" forecast of the future spot exchange rate, for five currencies relative to the dollar. This hypothesis provides a convenient norm for examining the erratic behavior of exchange rates; this erratic behavior represents an efficient market that is quickly incorporating new information into the current exchange rate. This hypothesis is analyzed using two distinct, but related, approaches. The first approach is based on a regression of spot rates on lagged forward rates. When using weekly data and a one month forward exchange rate, ordinary least squares regression analysis of market efficiency is incorrect. Econometric methods are proposed which allow for consistent (though not fully efficient) estimation of the parameters and their standard errors. This paper also presents a new approach for testing exchange market efficiency. This approach is based on a general time series process generating the spot and forward exchange rate. The hypothesis of efficiency implies a set of cross-equation restrictions imposed on the parameters of the time series model. This paper derives these restrictions, proposes a maximum likelihood method of estimating the constrained likelihood function, estimates the model and tests the validity of the restrictions with a likelihood ration statistic.

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1 Introduction

The hypothesis of efficiency has been used in many studies of the foreign exchange market. This hypothesis implies that there are no unexploited profit opportunities. In the foreign exchange market this implies that the forward rate summarizes all relevant and available information useful for forecasting the future spot rate. Analyzing this aspect of efficiency requires an equilibrium model of pricing in the foreign exchange market. Consequently, any empirical test of efficiency is a joint test of efficiency and the equilibrium model.

This paper will focus on two different methods of testing market efficiency. Section 2 will examine the issue of efficiency from the point of view of the standard regression model. This procedure emphasizes the regression of the spot rate on the lagged forward rate. Several econometric difficulties arise and must be overcome when the forecast horizon (one month) exceeds the sampling interval (one week). The stochastic structure of the error term may be interpreted as new information reaching the foreign exchange market. To analyze the nature of efficiency with this procedure requires an empirical analysis of the properties of the error term. This will be done in Section 3.

Section 4 will present a new, and alternative, procedure for analyzing the hypothesis of efficiency. This procedure is based on a time series analysis of the spot and one month forward rate. It is assumed that the spot and forward rate can be described by a bivariate stochastic process. The structure of the stochastic process provides a convenient method for extracting forecasts of the future spot rate as a function of all available information (given the model being assumed). The hypothesis of

market efficiency states that, in general, the expected value of the future spot rate is the current forward rate. Therefore, the parameters of the original stochastic process are not free, but must be constrained. The restrictions are highly nonlinear. Section 4 provides a computationally feasible method for calculating the likelihood function subject to these restrictions. The restrictions are then tested for five currencies relative to the dollar. Section 5 concludes the paper.

2 Econometric Testing and Procedures

Conventional tests of foreign exchange market efficiency focus on the relation between spot and lagged forward rates. (Assume, for now, that one month is exactly four weeks.) If one wants to forecast $\ln S_{t+4}$, based on information up to (and including) time t, then the following regression is appropriate:

$$\ln S_{t+4} = x'_t \beta + u_{t+4} \tag{1}$$

where x_t represents variables relevant for forecasting lnS_{t+4} , and where

The four week forward rate set on Tuesday is for delivery four weeks hence, also a Tuesday. However, a one month forward rate set on Tuesday is for delivery four weeks and two days hence, on a Thursday. The extra two days induces additional serial correlation, so the error term will be MA(4). (See also Stockman (1978).) Notice that if one examines $\ln S_{t+4}$ - $\ln S_t$, one would expect an MA(3) process, since the comparison is between spot rates on different Tuesdays.

Given that u_t can be written as an MA(3) process, one can write $u_t = \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \theta_3 \varepsilon_{t-3} = \theta(L) \varepsilon_t$. Notice that equation (2) does not require that x_t be strictly exogenous (at all leads and lags). Obtaining estimates of the β vector by ordinary least squares is equivalent to minimizing the sum of squared prediction errors. To test the forecasting ability of the forward rate, equation (1) will be restricted by requiring x_t to consist of a constant and lnF_t . Therefore, equation (1) may be rewritten as

$$lnS_{t+4} = a + blnF_t + u_{t+4}$$
 (1') where

 $E\left(u_{t+4}\colon \ln S_t,\ \ln S_{t-1},\ \dots,\ \ln F_t,\ \ln F_{t-1},\ \dots\right) = 0. \tag{2'}$ For future reference let $I_t = \{\ln S_t,\ \ln S_{t-1},\ \dots,\ \ln F_t,\ \ln F_{t-1},\ \dots\}.$ Restricting the x_t vector in this way will impose restrictions on the data that can be rejected. These restrictions test if the forward rate summarizes all information (and that the risk premium, if it exists, is such that equation (1') holds).

There are several difficulties involved in estimating equation (1') efficiently as a regression equation. The problem arises since $\ln F_t$ is not strictly exogenous (that is, $\ln F_t$ is a lagged endogenous variable) and the errors are serially correlated. Because of these two facts, one must be careful in applying generalized least squares. It does not appear that there exists a simple and efficient two step GLS procedure with lagged endogenous variables and moving average error terms. It is, however, possible to obtain consistent, though not fully efficient, estimates of a

and b by using ordinary least squares. 1 It is not fully efficient since one does not use the information that u_t is MA(3); it is, however, more efficient than dropping three-fourths of the observations.

A sufficient condition for the forward rate to be an unbiased forecast of the future spot rate is a=0 and b=1 in equation (1'). Two of the studies using weekly data with a forward rate of maturity greater than one week (Stockman 1978 used a one-month forward rate and Hansen and Hodrick 1979 used a three month forward rate) constrained, a priori, b=1.

$$\theta(L)^{-1} \ln S_{t+4} = a\theta(L)^{-1} + b\theta(L)^{-1} \ln F_t + \epsilon_{t+4}$$

Now, it is the case that $\boldsymbol{\varepsilon}_{t}$ is serially uncorrelated; however, in general it will be the case that

The nature of the inconsistency in this case can be easily seen (see Hansen 1979). Let u_t have an MA representation: $u_t = \theta(L)\varepsilon_t$, where $\theta(L)$ is invertible, with inverse $\theta(L)^{-1}$. Multiplying equation (1') by $\theta(L)^{-1}$ we have

²If unbiasedness means $E(S_{t+4}: I_t) = F_t$ and u_t is normally distributed in (3'), then it is easily shown that the "correct" null hypothesis is $a = -\frac{1}{2} \sigma_u^2$ and b = 1 (see Frenkel 1979). A difficulty is that to <u>state</u> the null hypothesis, one must make some distributional assumption on the residuals (normally, we make distributional assumptions when we want to <u>test</u> the null hypothesis (see Garber 1978)).

Stockman set b = 1 so that he could estimate the moving average parameters efficiently and Hansen and Hodrick set b = 1 to induce stationarity. However, constraining b = 1 may bias the other coefficient.

Much of the attention in the paper will be focussed on the residuals u_t . There are two reasons for this. The first, discussed earlier, is that if the forward rate is to be an efficient forecast of the future spot rate, then the residuals should be a pure forecast error. The second reason comes from considering the return from holding foreign currency. Decompose the total return from holding foreign currency, $\ln S_{t+4} - \ln S_t$, as follows:

$$\ln S_{t+4} - \ln S_{t} = (\ln S_{t+4} - E_{t} \ln S_{t+4}) + (E_{t} \ln S_{t+4} - \ln S_{t})$$
 (3)

where the notation $E_t x_s = E(x_s; I_t)$ is used. Many studies look at the total return (Poole 1967 and Bilson 1979). The second term on the right hand side, $E_t^{\ln S}_{t+4}$, is a known quantity (to the economic agent), it is the expected change as of time t in the exchange rate. The first term, $\ln S_{t+4} - E_t \ln S_{t+4}$, is a random variable that represents the unanticipated return from holding

Consider a simple example (no serial correlation) where we project (linearly) y_t on a constant x_0 , x_{1t} and x_{2t} : $E(y_t:x_0,x_{1t},x_{2t})=b_0+b_1x_{1t}+b_2x_{2t}$. Suppose we constrain b=1, then $E(y_t-x_{1t}:x_0,x_{2t})=a_0+a_2x_{2t}$. It can be shown that $b_2=cov(x_{2t},y_t)/var(x_{2t})$ and $a_2=b_2-cov(x_{2t},x_{1t})/var(x_{2t})$.

 $^{^2}$ See Roll and Solnick (1977, p. 167) for a similar decomposition.

foreign currency, due to new information which affects the exchange rate. Since agents are compensated for bearing uncertainty, one is led to focus on that term. But equation (1') states that $E_t lnS_{t+4} = a + blnF_t$; hence $lnS_{t+4} - E_t lnS_{t+4} = u_{t+4}$.

It was stated earlier that u_t can be written as $u_t = \theta(L)\varepsilon_t$, where $\theta(L)$ is a third degree polynomial in the lag operator L. Since one can write $u_t = \theta(L)\varepsilon_t$, equation (1') may be rewritten as

$$\ln S_{t+4} = a + b \ln F_t + \theta_3 \varepsilon_{t+1} + \theta_2 \varepsilon_{t+2} + \theta_1 \varepsilon_{t+3} + \varepsilon_{t+4}.$$
 (1")

Assuming the ε -shocks strike with equal weight over time, one would expect the θ 's to be approximately equal to 1. Appendix A provides an interpretation of the θ 's and the ε 's.

3 Econometric Results

Equation (1') is estimated for five currencies, with respect to the dollar, for the period April 1973 to May 1977. Ordinary least squares estimates of a and b are reported in Table 1. In all cases b is less than one. However, only in the case of the Netherlands and Germany is b significantly less than one. In addition, the constant term is significantly less than zero for the Netherlands and Germany, but insignificantly different from zero for Canada, Switzerland and the U.K. These results indicate a significant risk premium for

¹I wish to thank Alan C. Stockman for providing me with this data. See the Data Appendix for a description of the data.

only the Netherlands and Germany.

Having obtained consistent estimates of a and b from Table 1, a consistent estimate of u_t is obtained. An MA(4) process was fit to the OLS residuals. The results are reported in Table 1. θ_1 and θ_2 are generally within one standard deviation of unity and θ_3 is generally within two standard deviations of unity. Switzerland is the exception, where θ_1 , θ_2 , and θ_3 are all significantly less than 1.0. θ_4 is significantly less than 1.0, as expected, since ε_t is picking up "the last two days of the month." These results conform to one's prior notion of of θ_1 's.

As stated previously, b has often been constrained to be unity (Hansen and Hocrick 1979 and Stockman 1978). If b is in fact unity, then this method will provide efficient estimates of a and the θ 's. However, if the data rejects the assumption that b is unity, imposing this restriction will bias our results. Table 2 reports the estimates of a obtained from constraining b to be unity. In all cases, a is insignificantly different from 0. Estimates of θ_j are also reported in Table 2 for the case in which b is constrained to be unity. In this case, a and θ_j (j= 1, 2, 3, 4) are jointly estimated in an efficient manner; $\ln F_t$ was taken to the left hand side so that all right hand side variables (a constant) are strictly exogenous. The results are similar to those in Table 1, except that θ_3 is significantly different from unity for the Netherlands and Germany.

As stated previously, the time series behavior of the residuals is of great interest. In particular, does u_t follow and MA(4) process, or equivalently, is ε_t white noise? To test this, a number of tests of ε_t being white noise are reported. Durbin's periodogram test (Durbin 1969) provides a frequency domain test of the null hypothesis that ε_t is white noise, against the alternative hypothesis that ε_t is not white noise (PER in the tables). PER = 0 means that the actual cumulative periodogram does not differ

TABLE 1 $lnS_{t+4} = a + blnF_{t} + u_{t+4}$ $u_{+} \sim MA(4)$

		Germany —	Canada ————	Switzerland	United Kingdom
a	-0.230 (0.078)	-0.257 (0.075)	0.001 (0.000)	-0.084 (0.045)	0.013 (0.018)
b .	0.757 (0.081)	0.719 (0.082)	0.915 (0.079)	0.913 (0.045)	0.979 (0.023)
θ ₁	1.012 (0.064)	0.996 (0.064)	1.102 (0.056)	0.628 (0.069)	1.023 (0.067)
θ2	1.076 (0.073)	0.964 (0.073)	1.070 (0.065)	0.682 (0.069)	0.939 (0.084)
θ3	0.860 (0.071)	0.839 (0.070)	1.002 (0.064)	0.629 (0.068)	0.747 (0.083)
θ ₄	0.378 (0.064)	0.441 (0.061)	0.629 (0.056)	0.226 (0.069)	0.336 (0.068)
$\sigma_{\mathbf{u}}^{2}$	0.851	0.974	0.130	0.958	0.577
σ_{ε}^2	0.184	0.213	0.027	0.377	0.131
PER	0	0	0	0	0
Q(12)	10.7	7.4	13.8*	9.4	16.6*
Q(24)	23.7	20.1	30.0	19.0	30.8
Q(36)	30.9	30.7	34.0	41.5	34.4

NOTES: Standard errors are in parentheses. σ_u^2 and σ_ε^2 are in units of 10^{-3} . Both σ_u^2 and σ_ε^2 are calculated with back forecasting. PER gives the number of times (or the periods) that the actual cumulative periodogram exceeds the expected cumulative periodogram, at the 10 percent level of significance. Q(k) tests the null hypothesis that the first k autocorrelations are equal to zero. Q(k) is distributed as $\chi^2(k-q)$, where q is the number of parameters estimated. An asterisk (*) denotes significant at the 5 percent level of significance.

TABLE 2 $lnS_{t+4} = a + 1.0 lnF_{t} + u_{t+4}$ $u_{t} \sim MA(4)$

	Netherlands	Germany	Canada	Switzerland	United Kingdom
a	0.0036 (0.0044)	0.0024 (0.0048)	0.0007 (0.0018)	0.0024 (0.0044)	-0.0034 (0.0033)
θ ₁	0.9883 (0.0660)	0.9821 (0.0648)	1.1029 (0.0549)	0.6239 (0.0698)	1.0264 (0.0675)
θ2	1.0332 (0.0774)	0.9429 (0.0771)	1.0709 (0.0645)	0.6704 (0.0705)	0.9387 (0.0849)
θ ₃	0.8017 (0.0759)	0.7870 (0.0752)	1.0055 (0.0630)	0.6099 (0.0697)	0.7466 (0.0839)
θ ₄	0.3525 (0.0662)	0.4154 (0.0636)	0.6495 (0.0549)	0.2107 (0.0694)	0.3335 (0.0678)
σ <mark>2</mark> .	0.990	1.153	0.134	1.025	0.586
σ_{ε}^2	0.231	0.278	0.029	0.418	0.134
PER	0	0	0	0	0
Q(12)	6.8	3.5	14.3*	9.7	16.3*
Q(24)	21.1	19.7	30.6	20.0	31.2
Q(36)	32.7	32.1	34.7	43.8	35.6

NOTES: See notes to Table 1.

significantly from the expected cumulative periodogram, at any frequency. The Box Pierce Q-statistic, Q(k), tests the null hypothesis that the first k autocorrelations are equal to zero. It can be shown that Q(k) is distributed as $\chi^2(k-q)$, where q is the number of parameters estimated. So far, only a very broad alternative has been considered: ϵ_t is not white noise. It is possible to test more restrictive alternative hypotheses. One particular alternative that is considered is that u_t is MA(5).

The results of these tests of white noise are reported in Table 1. In all cases, Durbin's periodogram test indicates that $\varepsilon_{\rm t}$ is white noise (PER = 0 in the table). The Box-Pierce Q-statistic also indicates that $\varepsilon_{\rm t}$ is white noise for the Netherlands, Germany and Switzerland. However, for Canada and the U.K, the Box-Pierce Q(12) statistic of 13.8 and 16.6 indicates that there is a departure from white noise, at the 5 percent level of significance for these currencies. (Note that Q(12) is insignificant at the Q(24) and Q(36) are insignificant at the 5 percent level.)

To test if u_t is MA(5), an MA(5) process was fit to the OLS residuals. The results are reported in Table 3. One finds that θ_5 is statistically significant for all currencies except Canada and the U.K. Recall that Canada and the U.K. had significant Q(12) statistics. This would seem to imply that although for these currencies there is serial correlation in u_t beyond an MA(4), it is not of a moving average form. To test this assertion, one can perform a likelihood ratio test of whether one needs to go to an MA(5) process for u_t (over an MA(4)). The results of this test are reported in Table 4 under

¹The power of a test relates to the alternative hypothesis. A test may be powerful against some alternatives but less powerful against other alternatives. Durbin's periodogram test has good power against the alternative of white noise, however, there are more powerful tests against, for example, an MA(5) alternative.

TABLE 3 $lnS_{t+4} = a + blnF_{t} + u_{t+4}$ $u_{t} \sim MA(5)$

	Netherlands	Germany	Canada	Switzerland	United Kingdom
a	-0.230	-0.257	0.001	-0.084	0.013
	(0.078)	(0.075)	(0.000)	(0.045)	(0.018)
ъ	0.757	0.719	0.915	0.913	0.979
	(0.081)	(0.082)	(0.079)	(0.045)	(0.023)
θ ₁	0.999	1.009	1.100	0.677	1.033
	(0.068)	(0.070)	(0.071)	(0.070)	(0.071)
^θ 2	1.050	1.008	1.067	0.773	0.974
	(0.088)	(0.091)	(0.095)	(0.080)	(0.097)
^θ 3	0.928	0.912	0.996	0.778	0.819
	(0.093)	(0.095)	(0.098)	(0.080)	(0.103)
θ ₄	0.578	0.547	0.620	0.364	0.422
	(0.086)	(0.089)	(0.096)	(0.080)	(0.097)
^θ 5	0.222	0.122	0.006	0.171	0.086
	(0.065)	(0.066)	(0.069)	(0.067)	(0.069)
$\sigma_{\mathbf{u}}^{2}$	0.851	0.974	0.130	0.958	0.577
σ_{ε}^2	0.181	0.212	0.027	0.370	0.131
PER	0	0	0	0	0
Q(12)	3.8	4.4	13.7	5.5	14.2*
Q(24)	15.3	15.0	30.1	13.3	28.0
Q(36)	24.7	26.9	34.1	35.9	31.5

NOTE: See notes to Table 1.

TABLE 4
HYPOTHESIS TESTING RESULTS

Error	Variance	Theta
3.32	4.31	12.81
0.95	3.94	5.00
0.00	0.53	16.27
3.7 9	6.90	6.89
0.00	0.58	4.53
	3.32 0.95 0.00 3.79	3.32 4.31 0.95 3.94 0.00 0.53 3.79 6.90

NOTE: The column Error tests the hypothesis that u_t is MA(4) against MA(5). A likelihood ratio test is used, where $2\ln\chi$ is distributed $\chi^2(1)$, where $\left[\sigma_{-}^2(\text{MA4})\right]^{(T/2)}$

where $\lambda = \begin{bmatrix} \frac{\sigma_2^2(MA4)}{\sigma_\epsilon^2(MA5)} \end{bmatrix}^{(T/2)}$. The critical values are 2.71 (10 percent),

3.84 (5 percent) and 6.63 (1 percent). The column Variance tests the hypothesis that the variance of ϵ_t is equal in both periods ($\sigma^2(\text{PER1}) = \sigma^2(\text{PER2})$) against the hypothesis that they are unequal. An F-statistic is calculated as $F = s_1^2/s_2^2$, F is distributed as F(99,97). Critical values, using F(100,100), for the two sided alternative are: 0.719 < F < 1.39 (10 percent) and 0.629 < F < 1.59 (2 percent). To test if the variance decreases over time, the critical values are 1.39 (5 percent) and 1.59 (1 percent). To test if the variance increases over time, the critical values are 0.719 (5 percent) and 0.629 (1 percent). The column Theta tests the hypothesis that $\theta(\text{PER}) = \theta(\text{PER2})$. A χ^2 statistic can be calculated to test this hypothesis (see Morrison 1967). The critical values for $\chi^2(4)$ are 7.78 (10 percent), 9.49 (5 percent) and 13.3 (1 percent).

the column headed "Error." For the Netherlands and Switzerland an MA(5) yields significantly better results at the 10 percent level, but not significantly better results at the 5 percent level, as indicated by χ^2 values of 3.32 and 3.79, respectively. For Germany, Canada and the U.K. there is no significant improvement at the 10 percent level. In fact, for Canada and the U.K., the variance of $\varepsilon_{\rm t}$ is unchanged, reflected in χ^2 values of 0.000, thereby confirming our earlier assertion.

As stated earlier, another issue of interest concerns the behavior of the system over time. For example, can one assert in any meaningful way that the system has become less noisy over time? Also, have economic agents reacted to new information in the same way over time? To answer these questions, the sample period was divided into two equal halves (non-overlapping) and equation (1') was reestimated for each half. The results are presented in Tables 5 and 6. An F-statistic was calculated to test the hypothesis that σ_{ε}^2 is the same in both periods. The results of this calculation are reported in Table 4 under the column headed "Variance." In all cases one can reject the hypothesis (at the 10 percent and 2 percent level) that the variances are equal, due to the extreme values of the F reported. For the Netherlands, Germany and Switzerland one can accept the alternative (at the 5 percent and 1 percent level) that the variance has increased over time, as reflected in the large values of F. On the other hand, for Canada and the U.K., one can accept the alternative (at the 5 percent and 1 percent level) that the variance has increased over time, as reflected in the small values of F.

The reaction of economic agents to the new information coming to the market is summarized by the θ -vector. A χ^2 test can be used to test if the θ 's change over time. The result of such a test is reported in Table 4 under column headed "Theta." For the Netherlands and Canada, one can reject, at the

TABLE 5 $lnS_{t+4} = a + blnF_{t} + u_{t+4}$ $u_{t} \sim MA(4)$

(April 1973 - April 1975)

	Netherlands	Germany	Canada	Switzerland	United Kingdom
a	-0.231	-0.298	-0.001	-0.096	0.301
b	0.765	0.672	0.972	0.904	0.652
⁰ 1	0.972 (0.093)	0.988 (0.090)	0.978 (0.093)	0.506 (0.091)	0.981 (0.097)
θ2	1.017 (0.106)	0.924 (0.103)	0.906 (0.191)	0.660 (0.063)	0.849 (0.110)
^θ 3	0.799 (0.102)	0.827 (0.098)	0.847 (0.097)	0.835 (0.050)	0.831 (0.109)
θ ₄	0.341 (0.093)	0.459 (0.086)	0.402 (0.090)	0.430 (0.086)	0.414 (0.096)
σ_u^2	1.211	1.473	0.067	1.583	0.352
σ_{ϵ}^2	0.302	0.339	0.018	0.642	0.083
PER	0	0	0	0	0
Q(12)	5.1	4 3	12.6	9.8	9.3
Q(24)	15.7	16.1	24.2	18.8	20.3
Q(36)	22.0	23.4	3.2.5	37.4	25.4

NOTES: See notes to Table 1.

TABLE 6 $lnS_{t+4} = a + blnF_{t} + u_{t+4}$ $u_{t} \sim MA(4)$

(May 1975 - May 1977)

	Netherlands	Germany	Canada	Switzerland	United Kingdom
a	-0.259	-0.192	0.002	-0.170	0.069
ъ	0.730	0.792	0.919	0.820	0.879
θ1	1.140 (0.083)	1.056 (0.093)	1.232 (0.067)	0.866 (0.098)	1.010 (0.098)
θ2	1.269 (0.077)	1.121 (0.102)	1.283 (0.064)	0.950 (0.101)	0.930 (0.121)
θ3	1.177 (0.065)	0.942 (0.099)	1.230 (0.045)	0.836 (0.099)	0.715 (0.119)
θ4	0.598 (0.078)	0.414 (0.091)	0.782 (0.060)	0.282 (0.098)	0.313 (0.097)
$\sigma_{\mathbf{u}}^{2}$	0.487	0.451	0.194	0.325	0.495
σ_{ϵ}^2	0.070	0.086	0.034	0.093	0.142
PER	0	0	0	0	0
Q(12)	20.3*	10.1	8.5	10.1	8.5
Q(24)	26.0	17.1	15.9	18.2	23.3
Q(36)	29.2	19.8	22.1	24.9	28.2

NOTES: See notes to Table 1.

at the 5 percent level, the hypothesis that the θ 's are the same in both periods. For Germany, Switzerland and the U.K. one cannot reject the hypothesis that the θ 's are the same in both periods. As a general proposition, it appears that θ (period 2) is larger than θ (period 1).

In summarizing the results in Tables 1-6, it is helpful to look for any patterns that emerge. The θ -vector does appear to equal a vector of ones (except, of course, for θ_4). Switzerland is a striking exception since the θ 's are significantly less than one. In addition, there is a tendency for θ_j to decrease as j increases. Finally, although the slope is significantly less than one only for the Netherlands and Germany, the point estimates are always less than one. This might seem to indicate that in fact b < 1. Notice, however, that this is not an exact statistical statement since the five exchange rates are not independent. What this observation suggests is that pooling all five currencies might lead to more precise estimates. In fact, this is what Bilson (1979) finds in a slightly different context.

It is also possible to divide the sample into two groups: (1) Canada and U.K. (2) the Netherlands, Germany and Switzerland. For Canada and the U.K. the constant in equation (1') is negative, while for the others it is positive. For a given slope, this implies that the U.S. dollar is safer, with respect to the Canadian dollar and U.K pound, but riskier with respect to the Dutch guilder, German mark and the Swiss franc. Canada and the U.K. were the only countries that showed any indication of serial correlation in the $\varepsilon_{\rm t}({\rm Q}(12)$ was significant at the 5 percent level). This indicates that for these two countries ${\rm lnF}_{\rm t}$ did not summarize all information about the value of ${\rm lnS}_{\rm t+4}$. (It should be noted that all other tests of randomness indicated a lack of serial correlation in $\varepsilon_{\rm t}$.) Finally, $\sigma_{\rm c}^2$ increased in the second period for Canada and the U.K., while it decreased for the others. How, then, is Canada and the

U.K. different from the Netherlands, Germany and Switzerland? A major difference would seem to be that the U.S. dollar appreciated against the Canadian dollar and U.K. pound for the period as a whole, while it depreciated against the other currencies. Not coincidently, Canada and the U.K. had the highest rates of inflation for the whole period and each of the two subperiods.

To understand the change in the variance of the system (σ_{ϵ}^2) , one should consider some of the institutional changes. In March of 1973, Germany and the Netherlands agreed to fix their rates within 2.5 percent but to float against the dollar. Late 1973 witnessed the dramatic increase in the price of oil. In December 1975 (at the Rambouillet meeting) and January 1976 (in Jamaica) it became "official" that we were in a period of floating exchange rates; previously, there was some hope of a return to fixed exchange rates. Finally, there was the IMF support of sterling in late 1976: in June of 1976, a \$5 billion stand-by credit and in December of 1976, a \$3.9 billion loan.

4 A New Procedure

Equation (1') expressed $E(\ln S_{t+4}:I_t)$ as a linear function of $\ln F_t$: $E(\ln S_{t+4}:I_t) = a + b \ln F_t$. This is quite a strong assumption, and one would like to test it. One possibility is to include variables x_i in the regression equation (1') and test if the coefficients are significant (see, for example, Hansen and Hodrick 1979); one would like a more efficient method. In addition, one would like to obtain a more efficient estimate of b.

Assume that $\{s_t, f_t\}$ is a bivariate, linearly indeterministic,

covariance stationary stochastic process. 1 It will be assumed, in the empirical work, that s_t and f_t are the first differences of the logarithms of s_t and f_t . Under the assumption that $\{s_t, f_t\}$ is invertible, one can express $\{s_t, f_t\}$ as an infinite order bivariate autoregression. Assuming one can truncate the autoregression at lag M, one can write

$$s_{t} = \sum_{i=1}^{M} a_{i} s_{t-i} + \sum_{i=1}^{M} \beta_{i} f_{t-i} + w_{t}$$

$$(4a)$$

$$f_{t} = \sum_{i=1}^{M} \gamma_{i} s_{t-i} + \sum_{i=1}^{M} \delta_{i} f_{t-i} + v_{t}$$

$$(4b)$$

$$w_t = s_t - E(s_t; s_{t-1}, s_{t-2}, ..., f_{t-1}, f_{t-2}, ...)$$

$$v_t = f_t - E(f_t; s_{t-1}, s_{t-2}, ..., f_{t-1}, f_{t-2}, ...)$$

$$Ew_t w_{t-k} = \begin{cases} \sigma_w^2 & k = 0 \\ 0 & k \neq 0 \end{cases}$$

$$\mathbf{E}\mathbf{v}_{\mathbf{t}}\mathbf{v}_{\mathbf{t}-\mathbf{k}} = \begin{cases} \sigma_{\mathbf{v}}^{2} & \mathbf{k} = 0\\ 0 & \mathbf{k} \neq 0 \end{cases}$$

$$Ew_{t}v_{t-k} = \begin{cases} \sigma_{wv} & k = 0\\ 0 & k \neq 0 \end{cases}$$

See Sargent (1979b) for a good exposition of the general methodology. This assumption implies that the variances of s_t and f_t exist and are independent of t, the covariance between s_t and f_t exists and is a function of k only, and the mean values of s_t and f_t are zero.

To estimate $(\alpha, \beta, \gamma, \delta)$, rewrite equation (4) as a first order vector stochastic difference equation. Define the matrix A, and vectors \mathbf{x}_t and

Then, one can rewrite equation (4) as

$$x_{t} = A x_{t-1} + a_{t} . ag{5}$$

Defining $c = (1 \ 0 \dots 0)$ and $d = (0 \dots 0 \ 1 \ 0 \dots 0)$, rewrite (4), using (5), as

$$s_t = c A x_{t-1} + w_t$$

$$f_t = d A x_{t-1} + v_t.$$
(6)

Update equation (5) by + j to obtain

$$x_{t+j} = A x_{t+j-1} + a_{t+j}$$

$$= A[A x_{t+j-2} + a_{t+j-1}] + a_{t+j}$$

$$\cdot$$

$$\cdot$$

$$\cdot$$

$$= A^{j+1} x_{t-1} + A^{j} a_{t} + \dots + a_{t+j}$$
(7)

Taking expectations of both sides of (7), conditional on information up to t-1, I_{t-1} , one obtains

$$E(s_{t+1}|I_{t-1}) = A^{j+1} x_{t-1}.$$
 (8)

Recalling that $s_t = c A x_{t-1} + w_t$, one can calculate $E_{t-1}S_t$ by premultiplying both sides of (8) by the (row) vector c:

$$E(S_{t}|I_{t-1}) = E(c x_{t+j}|I_{t-1}) = c A^{j+1} x_{t-1}.$$
 (9)

The assumption that f_t summarizes all information implies that

$$E(s_{t+4}|I_{t-1}) = b E(f_t|I_{t-1}).$$

Equation (6) implies that

$$b E(f_t | I_{t-1}) = b(dA) x_{t-1}$$
 (10)

Therefore, by equating equations (9) snd (10), the following set of crossequation restrictions are obtained:

$$b(dA) = c A5 . (11)$$

The assumption that the forward rate is an unbiased estimate of the future spot rate implies b = 1. Therefore, the restrictions embodied in

(11) become

$$dA = cA^{5}. (12)$$

Under the hypothesis that $\{w_t^{}, v_t^{}\}$ is bivariate normal, the likelihood function of a sample of size T of $\{w_t^{}, v_t^{}\}$ can be written

$$L(\alpha, \beta, \gamma, \delta | \{s_t\}, \{f_t\}) = (2\pi)^{-T} |V|^{-T/2} \exp(-1/2\sum_{t=1}^{T} e_t' V^{-1} e_t)$$
 (13)

where

$$e_t = \begin{bmatrix} w_t \\ v_t \end{bmatrix}$$
 $V = E e_t e_t'.$

Maximizing (13) unconstrainded is equivalent to estimating (4) by least-squares (to obtain efficient standard errors, one would use Zellner's unrelated regression).

The restrictions implied by equations (11) and (12) are highly non-linear. First, consider estimation strategies for the restriction implied by b=1. Sargent (1979b) proposes two alternative estimation strategies. The first method requires estimating row one of A, equation (4a), by least squares. Then, the (M+1) st row of A, equation (4b), is calculated using an iterative procedure. Form a preliminary estimate of A, call if A_0 , by setting row M + 1 to a row of zeroes, and all other rows to their known (or consistent) values. Calculate the (M+1)st row of A, at iteration i + 1, as

$$(\text{row M+1})_{i+1} = dA_{i+1} = c A_i^5$$
 (14)

where A_i is the estimate of A on the i'th iteration. At each step in forming A_i , all rows (except the (M+1)st) are kept equal to the corresponding row of A_0 . If this procedure converges, it will find an A that satisfies (12). The condition for convergence is that the roots of A be

less than one in modulus. Since the elements of row 1 are consistently estimated by least squares, the (M+1)st row will be consistently estimated as a function of the first row of A.

Define the solution to the iteration on (14) as the (set) function Φ :

$$(\gamma, \delta) = \Phi(\alpha, \beta) \tag{15}$$

 Φ maps the α 's and β 's into a set of γ 's and δ 's that satisfy restriction (12). Hence, one (consistent) estimator of γ , δ is $\Phi(\alpha, \beta)$.

Estimating equation (4), with restriction (11) imposed, is analogous. As before, begin by estimating the first row of A, equation (4a), by least squares. An initial guess for b is obtained from Table 1. Then, the (M+1)st row of A, equation (4b), is calculated using an iterative procedure. In a manner similar to before, one can obtain as a solution to the iteration procedure the set function $\Phi: \Phi(\alpha, \beta, b) = (\gamma, \delta)$. Φ maps the α 's, β 's and b into a set of γ 's and δ 's that satisfy restriction (11).

Under the restriction (12) (equivalently (15)), the likelihood function in (13), $L(\alpha, \beta, \gamma, \sigma | \{s_t\}, \{f_t\})$, becomes a function only of the α 's and β 's. As Wilson (1973) argues, maximum likelihood estimates with an unknown V, are obtained by minimizing $|\hat{V}|$, with respect to the α 's and β 's, where

$$|\hat{V}| = \frac{1}{T} |\sum_{t=1}^{T} e_t(\alpha, \beta) e_t(\alpha, \beta)'|$$

and the $e_t(\alpha,\beta)$, the residuals from (4), are functions of the α 's and β 's only, since they were calculated from (4) with (12) (equivalently (15) imposed.

A derivative free nonlinear minimization routine can be used to estimate (2.8) under the restriction (2.16) or (2.15). The IMSL subroutine

ZXMIN, which uses a quasi-Newton method, was used. Generally, 600 iterations were required to obtain three significant digits. The least squares estimates of α and β were used as starting values.

Tables 7-11 report three estimates of equation (4) under various assumptions for the five currencies vis-a-vis the U.S. dollar. The tables report estimates of the bivariate autoregression (4) unconstrained, the maximum likelihood estimates that impose (12) (b=1) and the maximum likelihood estimates that impose (13) (b free). Also reported are the row sums of the α 's, β 's, γ 's and δ 's. The likelihood ratio statistic, which is distributed $\chi^2(8)$, and the marginal significance level, which is the probability that a random variable that is distributed $\chi^2(8)$ attains a value greater than or equal to the test statistic, are also reported.

According to the likelihood ratio statistic, the hypothesis is generally rejected. Only for Germany, with b free, is the marginal significance level greater than 0.02. The assumption that $\{s_t, f_t\}$ is stationary is equivalent to the assumption that the characteristic roots of A are all less than one in modulus (Sargent (1979a), p. 273). The roots of A were calculated for all three sets of estimates and all were found to be less than one in modulus.

There appears to be a number of regularities that can be found in these results, some of which may be related to the cause for rejection. One regularity concerns the sign pattern of the coefficients. In all cases but two (Canada and the U.K.), the sum of the α_i 's and the sum of the δ_i 's are negative, while the sum of the β_i 's and the sum of the γ_i 's are positive. Recall that the α 's are the coefficients on lagged s_t 's and the β 's are the coefficients on lagged s_t 's in the s_t equation, while the γ 's are the coefficients on lagged s_t 's and the δ 's are the coefficients on

TABLE 7

NETHERLANDS: ESTIMATES OF BIVARIATE AUTOREGRESSION UNRESTRICTED AND RESTRICTED

					
j	1	2	3	4	Row Sum
		Unrestri	cted Estimates	<u>.</u>	
a,	0.01913	-0.04513	-0.01726	-0.00722	-0.05049
βį	0.26103	0.08057	0.06862	-0.02894	0.38128
Υį	0.82962	0.49743	0.20908	0.00174	1.53787
αj βj Υj δj	-0.51371	-0.35106	-0.14112	0.01910	-0.98679
•	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$	303*10 ⁻⁴ 8.3 ⁴ 9.7	45*10 ⁻⁵) v̂	= 5.692*10 ⁻⁹	
,	,	Maximum Lik	elihood Estima b=l	ites .	
α,	-0.56550	-0.59600	-0.40654	-0.40114	-1.96918
β.	0.68043	0.56195	0.44296	0.16306	1.84840
Υ.	0.29193	0.07700	0.02809	0.04198	0.43900
αj βj Υj δj	-0.17457	-0.05475	-0.04048	-0.01706	-0.25686
•	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$	541*10 ⁻⁴ 1.06	$\begin{vmatrix} 61*10^{-5} \\ 59*10^{-4} \end{vmatrix}$ $ \hat{v} $	= 6.596*10 ⁻⁹	
	ihood ratio sta nal significan				
			elihood Estima b free	<u>tes</u>	
αį	-0.65142	-0.65475	-0.29087	-0.18303	-1. 78007
βį	0.82390	0.55780	0.25424	0.03786	1.67380
Υ _i	0.32057	0.10130	0.01639	0.06781	0.50607
α _j β _j γ _j δ _j	-0.11494	-0.08055	-0.07529	-0.01403	-0.28481
		577*10 ⁻⁴ 1.09		= 6.492*10 ⁻⁹	
	ihood ratio stana nal significan		-		

TABLE 8

GERMANY: ESTIMATES OF BIVARIATE AUTOREGRESSION UNRESTRICTED AND RESTRICTED

j	1	2	3	4	Row Sum
		<u>Unrestri</u>	cted Estimates	<u> </u>	
α,	-0.06783	-0.15063	-0.06351	-0.00627	-0.28824
βį	0.30407	0.22275	0.15479	-0.02938	0.65223
Υ.,	0.70532	0.43141	0.27823	0.00165	1.41661
αj βj Υj δj	-0.44493	-0.31663	-0.16010	0.03287	-0.88879
•	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & \mathbf{v} \end{bmatrix}$	573*10 ⁻⁴ 9.8.	31*10 ⁻⁵)	0.03287 $7 = 8.488 * 10^{-9}$	
	•		elihood Estima b=1		
α	-0.56630	-0.62942	-0.49703	-0.39033	-2.08308
J β ₄	0.70566	0.66585	0.54469	0.14558	2.06178
Λ.	0.23349	0.04501	-0.00001	0.00329	0.28178
αj βj Υj δj	-0.12809	-0.01655	-0.00303	-0.00123	-0.14890
3	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & \mathbf{v} \\ \mathbf{v} \end{bmatrix}$	732*10 ⁻⁴ 1.1°	79*10 ⁻⁴	$ = 9.680*10^{-9}$	
	ihood ratio st nal significan				
			elihood Estima b free	<u>ites</u>	
αj	-0.48035	-0.63593	-0.54612	-0.38979	-2.05219
βį	0.69258	0.65924	0.52844	0.15190	2.03216
Υį	0.31682	0.07705	-0.00284	-0.01249	.37854
β j Y _j δ	-0.18501	-0.02871	0.01123	0.00487	19762
•		b =	= 0.66335		
	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$	700*10 ⁻⁴ 1.13	$\begin{pmatrix} 30*10^{-5} \\ 96*10^{-4} \end{pmatrix}$ \hat{v}	$ = 9.280*10^{-9}$	
	ihood ratio sta nal significan	atistic = 18.0	019		•

TABLE 9

CANADA: ESTIMATES OF BIVARIATE AUTOREGRESSION

UNRESTRICTRED AND RESTRICTED

				<u> </u>	
<u>t</u>	1	2	3	4	Row Sum
		<u>Unrestri</u>	cted Estimat	es	
α	0.14948	0.07733	0.05981	-0.18817	0.09845
αj βj Υj δj	0.07164	-0.07935	0.02268	0.09671	0.11168
Υį	0.82945	0.30516	0.15284	-0.02884	1.25861
δį	-0.45814	- 0.26949	-0.11163	0.04070	-0.79856
	$\hat{\mathbf{v}} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$	199*10 ⁻⁵ 1.1 1.2 Maximum Lik	14*10 ⁻⁵) 40*10 ⁻⁵) elihood Estir	$ \hat{\mathbf{v}} = 1.499 * 10^{-10}$	
		THE PARTITION LIKE	b=1	illa ces	
αį	-0.46541	-0.06324	0.25763	-0.11134	-0.38236
αj βj	0.39378	-0.11220	-0.06007	-0.02458	0.19693
Υį	0.26696	-0.01351	-0.07107	0.02913	0.21151
Υj δj	-0.11470	0.01886	0.01490	0.00643	-0.07451
-	$\hat{\mathbf{v}} = \begin{cases} 2 \cdot \mathbf{v} \\ 1 & \text{otherwise} \end{cases}$		08*10 ⁻⁵)	$ \hat{\mathbf{v}} = 2.144 * 10^{-10}$	

Likelihood ratio statistic - 72.246 Marginal significance level = 0.0001

		Maximum Like		mates	
			free		
αį	-0.47036	-0.11258	0.20141	-0.11788	-0.49941
βj	0.37960	-0.07881	-0.07815	0.01220	0.23484
Ϋ́j	0.29606	-0.00506	-0.06488	0.03605	0.26217
δj	-0.15633	0.02658	0.02424	-0.00374	-0.10925
•		b =	0.87230		
	$\hat{V} = \begin{cases} 2 \cdot \\ \end{cases}$	704*10 ⁻⁵ 1.51	$1*10^{-5}$ $6*10^{-5}$	$ \hat{\mathbf{v}} = 2.085*10^{-10}$	

Likelihood ratio statistic = 66.696 Marginal significance level = 0.0001

TABLE 10

SWITZERLAND: ESTIMATES OF BIVARIATE AUTOREGRESSION UNRESTRICTED AND RESTRICTED

j	1	2	3	4	Row Sum
		<u> Unrestri</u>	cted Estimate	es	-
α	-0.09582	0.00814	-0.01271	-0.01044	-0.11083
βį	0.09477	0.08734	0.10093	-0.07744	0.20560
Υį	0.82700	0.80629	0.34803	0.00003	1.98135
α _j β _j Υ _j δ _j	-0.83059	-0.50919	-0.16071	-0.08883	-1.58932
J	$\hat{\mathbf{v}} = \begin{pmatrix} 2 \cdot \\ \end{pmatrix}$	1.1 1.6	93*10 ⁻⁴) 96*10 ⁻⁴	$ \hat{\mathbf{v}} = 2.237*10^{-8}$	
		Maximum Lik	elihood Estir b=l	<u>mates</u>	
α	-0.41943	-0.17910	0.06281	-0.16359	-0.69931
βį	0.36243	0.09490	0.04269	0.09038	0.08255
Υ.,	0.20600	0.03741	-0.03392	0.04641	0.25590
αj βj Υj δj	-0.14204	-0.01189	-0.00320	-0.02565	-0.18278
J	$\hat{\mathbf{v}} = \begin{bmatrix} 2 \cdot \mathbf{v} \end{bmatrix}$	419*10 ⁻⁴ 1.4 2.3	92*10 ⁻⁴ 90*10 ⁻⁴	$ \hat{\mathbf{v}} = 3.555*10^{-8}$	
	ihood ratio st nal significan				
			elihood Estir b free	nates	
αj	-0.62217	-0.50351	-0.09868	-0.13233	-1.35669
	0.50449	0.36383	0.12815	0.13226	1.12873
Υį	0.41899	0.23797	-0.00424	0.08930	0.74202
βj Υj δj	-0.40328	-0.12797	-0.01568	-0.08925	-0.63618
•		Ъ :	= 0.69214		
	$\hat{\mathbf{v}} = \begin{cases} 2.6 \end{cases}$	649*10 ⁻⁴ 1.49	98*10 ⁻⁴ 93*10 ⁻⁴	$ \hat{\mathbf{v}} = 3.035*10^{-8}$	
Likel	ihood ratio st				

Likelihood ratio statistic = 61.599 Marginal significance level = 0.0001

TABLE 11
UNITED KINGDOM: ESTIMATES OF BIVARIATE AUTOREGRESSION
UNRESTRICTED AND RESTRICTED

		2	3	4	Row Sum
		<u>Unrestr</u>	icted Estimat	tes	
x.	-0.02734	0.11613	0.04996	-0.00269	0.13606
βį	0.07475	0.02602	-0.13810	0.32083	0.28350
Y ₄	0.69528	0.47395	0.26807	-0.00221	1.43509
^α j βj Υj δj		-0.34317			-0.75428
3	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & \mathbf{v} \\ \mathbf{v} & \mathbf{v} \end{bmatrix}$	055*10 ⁻⁴ 6.	942*10 ⁻⁵)	$ \hat{\mathbf{v}} = 2.695*10^{-9}$	
	•	Maximum Li	kelihood Est: b=1	imates	
x .	-0.63784	-0.44721	-0.03676	-0.12006	-1.24187
ີ່ 3ຸ .	0.52810	0.28584	0.09796	0.10231	1.01421
۲. ۲	0.25553	0.14629	-0.02008	0.04839	0.43013
x j g j s	-0.22631	-0.06691	-0.00974	-0.04123	-0.34419
J	$\hat{\mathbf{v}} = \begin{pmatrix} 2 \cdot \mathbf{v} \\ 1 & 1 \end{pmatrix}$	682*10 ⁻⁴ 1.	657*10 ⁻⁴ 224*10 ⁻⁴	$ \hat{\mathbf{v}} = 3.217*10^{-8}$	
	nood ratio stal				
		Maximum Li	kelihood Esti b free	imates	
x i	-0.5770	-0.1623	0.0426	-0.0297	-0.7264
3;	0.5073	0.0729	-0.0625	-0.0607	0.4570
γ _i	0.0936	0.0080	-0.0041	0.0030	0.1005
j ³ j ^Y j Sj	-0.0263	-0.0237	0.0069	0.0062	-0.0369
J		ъ	= 0.8697		
	$\hat{\mathbf{v}} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$	301*10 ⁻⁴ 9.3	136*10 ⁻⁵)	$ \hat{\mathbf{v}} = 3.733*10^{-9}$	

Likelihood ratio statistic - 65.814 Marginal significance level lagged f_t 's in the f_t equation. In other words, the "own" lagged coefficients are negative while the "cross" lagged coefficients are positive. This indicates that if s_t is high this period, s will be lower <u>next</u> period and f will be higher <u>next</u> period. For the unrestricted estimates, the sum of the α 's and β 's (the parameters of the s_t equation) and the sum of the γ 's and δ 's (the parameters of the f_t equation) are both positive. This fact, in conjunction with the previous facts, indicate that the positive "cross" effects dominate the negative "own" effects. However, when one examines the restricted (b=1) estimates, one observes a difference. In this case, the sum of the parameters of the f_t equation is negative, while the sum of the parameters of the f_t equation is positive. That is, for the restricted estimates, the negative "own" effects dominate the positive "cross" effects for the f_t equation, but not for the f_t equation. Finally, both the sum of the parameters of the f_t equation decrease in going from the unrestricted to the restricted estimates.

5. Conclusions

Many studies of the foreign exchange market assume that the market is efficient. This implies that there are no unexploited profit opportunities. In terms of the foreign exchange market, this means that the forward rate summarizes all relevant, and available, information about the future spot rate. If one desires to test such an assumption, one requires an equilibrium model of pricing in the foreign exchange market which includes specifying an information set. Consequently, any empirical test of market efficiency is a joint test of market efficiency and the equilibrium model being used. Therefore, a rejection of the empirical test may reflect a rejection of market efficiency, or a rejection of the model being used, or both.

The first section of this paper examined the regression $\ln S_{t+4} = a + b \ln F_t + u_{t+4}$. The results were mixed, but generally favorable. For Canada, Switzerland and the U.K. the hypothesis that a = 0, b = 1 could not be rejected; for the Netherlands and Germany, the hypothesis could be rejected. More importantly, for the Netherlands, Germany and Switzerland, the residuals behaved in a random fashion, indicating that the forward rate does summarize all available information. Canada and the U.K., on the other hand, had a significant Q(12) statistic, indicating a departure from randomness. When the restriction b=1 was imposed, the constant term was insignificantly different from zero and the residuals behaved in a similar fashion to when b was free.

The second half of this paper examined a bivariate autoregression for $(\ln S_t - \ln S_{t-1}, \ln F_t - \ln F_{t-1})$; the results were unfavorable. It is worth noting that the null hypothesis is a single point in the parameter space. Consequently, when this single point is rejected, what \underline{model} is to be accepted as an alternative: it takes a model to reject a model. What was shown is that the model proposed is not compatible with the data; not that the hypothesis of market efficiency is to be rejected. What are some possible reasons for this rejection?

The reason could be purely econometric: For example, was $\left\{s_t, f_t\right\}$ a linearly indeterministic stationary stochastic process? The simple evidence indicates that s_t and f_t were stationary. However, Section 3 showed that σ_ε^2 was not constant over the sample period and so $\left\{s_t, f_t\right\}$ might not have been stationary: the variance might have changed over time.

The other reason questions the theory used in developing the hypotheses. As Michael Jensen stated, in a slightly different context (1978, p. 95): ". . . as our econometric sophistication increases, we are beginning to find inconsistencies that our cruder data and techniques missed in the past," and "the eventual resolution of these anomalies will result in more precise and more general theories of market efficiency and equilibrium models of the determination of asset prices under uncertainty" (Jensen 1978, p.96). The theory also relies on the assumption of a constant risk premium. If the risk premium was not constant--perhaps it followed some (low order) stochastic process or was a function of other variables -- then the model was misspecified. In addition, Harris and Purvis (1978) construct a model in which a distinction is drawn between permanent and transitory shocks. Consider, for example, a permanent shock such as the oil crisis. People initially interpreted this as a temporary shock, and only over time was it perceived to be a permanent shock. It is only over time, while people accumulated new information, that the exchange rate (gradually) attained its new level. Consequently, looking at a time series we observe serial correlation. However, this serial correlation simply reflects people eliminating their initial confusion of whether the oil shock was permanent or transitory; it does not represent irrational behavior.

Finally, much of the theory is taken directly from the theory of efficient markets in finance (see Fama 1969). There are a number of differences that need to be considered. The foreign exchange market is much less regulated than the U.S. stock market. However, there is much more direct government intervention in terms of manipulating exchange

rates than in the U.S. stock market. Finally, there is a stronger presumption that the equilibrium stock price is constant than that the equilibrium exchange rate is constant.

Data Appendix

Five exchange rates (with respect to the dollar) will be examined. These currencies are (1) the Dutch guilder (the Netherlands), (2) the German mark, (3) the Canadian dollar, (4) the Swiss franc and (5) the U.K. pound. The period to be analyzed is April 24, 1973 to May 5, 1977. The ending date was arbitrary, while the starting date reflected the fact that there appeared to be a structural change in the international monetary system in March 1973, when the EEC agreement to stabilize the dollar value of their currencies within a 2.25 percent band was abandoned (see Frenkel 1978, Frenkel-Levich 1977, and Levich 1977 for evidence on this observation). Weekly observations were obtained (from the International Monetary Market Yearbook) on bid spot and one month forward rates on the New York foreign exchange market. Forward rates are (generally) observed on Tuesdays, while spot rates are observed on Thursdays. The reason for this staggering of observations is that one month is equal to (approximately) four weeks and two days. See Hakkio (1979) for a more detailed description of the data and some summary statistics for the whole period and its two subperiods.

Appendix A

This appendix attempts to provide an interpretation of the θ -vector and ε to Recall that $s_t = \ell \, n S_t - \ell \, n S_{t-1}$, $f_t = \ell \, n F_t - \ell \, n F_{t-1}$, and $\ell \, n S_{t+4} = a + b \ell \, n F_t + u_{t+4}$, where $u_{t+4} = \theta(L) \, \varepsilon_{t+4}$.

$$E_{t}^{lnS}_{t+4} = a + b^{ln}F_{t}$$

$$E_{t}^{lnS}_{t+3} = a + b^{ln}F_{t-1} + \theta_{3}\varepsilon_{t}$$

$$E_{t}^{s}_{t+4} = bf_{t} - \theta_{3}\varepsilon_{t}$$
(A1)

Therefore, market efficiency implies

$$E_{t-1}s_{t+4} = bE_{t-1}f_t$$
 (A2)

Assume that $\{s_t,f_t\}$ is a bivariate, linearly indeterministic, covariance stationary stochastic process. Therefore, using the Wold decomposition theorem, one can write $\{s_t,f_t\}$ as an infinite order moving average process:

$$s_{t} = \alpha (L)w_{t} + \beta (L)v_{t}$$

$$f_{t} = \gamma (L)w_{t} + \delta (L)v_{t}$$
(A3)

where $\alpha(L), \beta(L), \gamma(L)$ and $\delta(L)$ are one-sided polynomials in the lag operator L,

$$w_t = s_t - E(s_t : s_{t-1}, s_{t-2}, ..., f_{t-1}, f_{t-2}, ...)$$
 $v_t = f_t - E(f_t : s_{t-1}, s_{t-2}, ..., f_{t-1}, f_{t-2}, ...)$

 $^{^1\}text{What}$ is required is a transformation to induce stationarity. This is one such transformation, an alternative would be to consider $^\ell n^S_{t+4}$ - $^\ell n^S_{t}$ and ℓn^F_{t} - ℓn^S_{t} . However, such a transformation means one cannot estimate b.

$$Ew_{t} w_{t-k} = \begin{cases} \sigma^{2}_{w} & k = 0 \\ 0 & k \neq 0 \end{cases}$$

$$Ev_{t} v_{t-k} = \begin{cases} \sigma^{2}_{v} & k = 0 \\ 0 & k \neq 0 \end{cases}$$

$$Ev_{t} v_{t-k} = \begin{cases} \sigma_{wv} & k = 0 \\ 0 & k \neq 0 \end{cases}$$

$$Ew_{t} v_{t-k} = \begin{cases} \sigma_{wv} & k = 0 \\ 0 & k \neq 0 \end{cases}$$

$$\alpha(0) = \delta(0) = 1$$
 and $\beta(0) = \gamma(0) = 0$.

Using the Weiner-Kolmogorov prediction formulas, one obtains

$$E_{t-1} s_{t+4} = \begin{bmatrix} \frac{\alpha(L)}{L^5} \\ L^5 \end{bmatrix} w_{t-1} + \begin{bmatrix} \frac{\beta(L)}{L^5} \\ L^5 \end{bmatrix} v_{t-1}$$
(A4)

Using equation (A3), one can calculate bE_{t-1} f_t :

$$bE_{t-1} f_t = b \begin{bmatrix} \gamma(L) \\ L \end{bmatrix} + w_{t-1} + b \begin{bmatrix} \delta(L) \\ L \end{bmatrix} + v_{t-1}$$
 (A5)

Therefore, market efficiency - equation (A2) - implies the following set of cross equation restrictions:

$$\begin{bmatrix} \frac{\alpha(L)}{L^5} \\ + \end{bmatrix} = b \begin{bmatrix} \frac{\gamma(L)}{L} \\ + \end{bmatrix} + \begin{bmatrix} \frac{\beta(L)}{L} \\ + \end{bmatrix} = b \begin{bmatrix} \frac{\delta(L)}{L} \\ + \end{bmatrix} + \begin{bmatrix}$$

One would next like to use equations (A3) and (A6) and equation (1') of the text the express the θ 's as a function of the α 's, β 's, γ 's, δ 's, σ_w^2 , σ_v^2 and σ_{wv} and to express ε_t as a function of these same variables plus the history of w_t and v_t . However, it seems that this is not possible. Define z_{t+4} to be the forecast error: $z_{t+4} = s_{t+4} - E_{t-1} s_{t+4}$. It is easy to show that z_{t+4} can be written, using (A6), as

$$z_{t+4} = s_{t+4} - E_{t-1} s_{t+4} = w_{t+4} + (\alpha_1 w_{t+3} + \beta_1 v_{t+3}) + (\alpha_2 w_{t+2} + \beta_2 v_{t+2}) + (\alpha_3 w_{t+1} + \beta_3 v_{t+1}) + (\alpha_4 w_t + \beta_4 v_t)$$
(A7)

Therefore, z_{t+4} can be expressed as an MA(4) process, by virtue of it being a 5-step ahead predictor. Using (1'), z_{t+4} can also be written as

$$z_{t+4} = s_{t+4} - E_{t-1} s_{t+4} = (\ln s_{t+4} - E_{t-1} \ln s_{t+4}) - (\ln s_{t+3} - E_{t-1} \ln s_{t+3})$$

$$= u_{t+4} - u_{t+3} + b(f_t - E_{t-1} f_t)$$

$$= \varepsilon_{t+4} + (\theta_1 - 1)\varepsilon_{t+3} + (\theta_2 - \theta_1)\varepsilon_{t+2} + (\theta_3 - \theta_2)\varepsilon_{t+1}$$

$$+ \theta_3\varepsilon_t + b(f_t - E_{t-1} f_t)$$
(A8)

Equation (1') provides no expression for $(f_t - E_{t-1} f_t)$. Using (A3), equation (A8) can be rewritten as

$$z_{t+4} = \varepsilon_{t+4} + \phi_1 \varepsilon_{t+3} + \phi_2 \varepsilon_{t+2} + \phi_3 \varepsilon_{t+1} + \phi_4 \varepsilon_t + bv_t$$
 (A8')

It is reasonable to expect that ε_t and v_t are at least contemporaneously correlated. To determine ϕ_1 , ϕ_2 , ϕ_3 , ϕ_4 (and hence θ_1 , θ_2 , θ_3), and σ_ε^2 one would normally next calculate the autocovariogram of z_{t+4} based on equation (A7) and equation (A8'); however, v_t appears in both (A7) and (A8'). Proceeding with

this procedure, one obtains $c(\tau) = Ez_{t} z_{t-\tau}$, based on (A7):

$$c(0) = (1 + \alpha_1^2 + \alpha_2^2 + \alpha_3^2 + \alpha_4^2) \sigma_w^2 + (\beta_1^2 + \beta_2^2 + \beta_3^2 + \beta_4^2) \sigma_v^2$$

$$+ 2(\alpha_1\beta_1 + \alpha_2\beta_2 + \alpha_3\beta_3 + \alpha_4\beta_4)\sigma_{wv}$$

$$c(1) = (\alpha_1 + \alpha_2 \alpha_1 + \alpha_3 \alpha_2 + \alpha_4 \alpha_3) \sigma_w^2 + (\beta_2 \beta_1 + \beta_3 \beta_2 + \beta_4 \beta_3) \sigma_v^2$$

$$+ (\alpha_2 \beta_1 + \alpha_3 \beta_2 + \alpha_4 \beta_3 + \beta_1 + \beta_2 \alpha_1 + \beta_3 \alpha_2 + \beta_4 \alpha_3) \sigma_{wv}$$
(A9)

$$c(2) = (\alpha_2 + \alpha_3 \alpha_1 + \alpha_4 \alpha_2) \sigma_w^2 + (\beta_3 \beta_1 + \beta_4 \beta_2) \sigma_v^2$$

$$+ (\alpha_3 \beta_1 + \alpha_4 \beta_2 + \beta_2 + \beta_3 \alpha_1 + \beta_4 \alpha_2) \sigma_{wv}$$

$$c(3) = (\alpha_3 + \alpha_4 \alpha_1) \ \sigma_w^2 + \beta_4 \beta_1 \sigma_v^2 + (\alpha_4 \beta_1 + \beta_3 + \beta_4 \alpha_1) \ \sigma_{wv}$$

$$c(4) = \alpha_4 \sigma^2 + \beta_4 \sigma_{wv}$$

For equation (A8'), one obtains (assuming v_t and ε_t are only contemporaneously correlated):

$$c(0) = (1 + \phi_1^2 + \phi_2^2 + \phi_3^2 + \phi_4^2) \sigma_{\epsilon}^2 + b^2 \sigma_{v}^2 + \phi_4 b \sigma_{\epsilon v}$$

$$c(1) = (\phi_1 + \phi_1 \phi_2 + \phi_2 \phi_3 + \phi_3 \phi_4) \sigma_{\epsilon}^2 + \phi_3 b \sigma_{\epsilon v}$$

$$c(2) = (\phi_2 + \phi_1 \phi_3 + \phi_2 \phi_4) \sigma_{\epsilon}^2 + \phi_2 b \sigma_{\epsilon v}$$
(A10)

$$c(3) = (\phi_3 + \phi_1 \phi_1) \sigma_{\varepsilon}^2 + \phi_1 b \sigma_{\varepsilon v}$$

$$c(4) = \phi_4 \sigma_{\varepsilon}^2 + b\sigma_{\varepsilon v}$$

Equating equations (A9) and (A10) yields five nonlinear equations in the unknown parameters $P^{u} = \{\theta_{1}, \theta_{2}, \theta_{3}, \sigma_{\varepsilon}^{2}, \sigma_{\varepsilon v}, b\}$ (the set $\{\phi_{1}, \phi_{2}, \phi_{3}, \phi_{4}\}$ is a

transformation of the three parameters θ_1 , θ_2 , θ_3); the known parameters are $p^k = \{\alpha_1, \alpha_2, \alpha_3, \alpha_4, \beta_1, \beta_2, \beta_3, \beta_4, \sigma_w^2, \sigma_v^2, \sigma_{wv}^2\}$. Therefore, if a solution exists, and if it is unique, it can be written as

$$P^{u} = F(P^{k}) \tag{A11}$$

Since z_{t+4} is an MA(4) process, one can write $z_{t+4} = \Psi(L)\eta_{t+4}$, where $\Psi(L)$ is a fourth degree polynomial in L. Assuming $\Psi(L)$ is invertible, and equating (A7) to $\Psi(L)\eta_{t+4}$, one obtains

$$\eta_{t+4} = \frac{\alpha'(L)}{\Psi(L)} w_{t+4} + \frac{\beta'(L)}{\Psi(L)} v_{t+4}$$
(A12)

where the definitions of $\alpha'(L)$ and $\beta'(L)$ are obvious from (A7). Therefore, η_{t+4} is an infinite order distributed lag of w_{t+4} and v_{t+4} . One would have preferred being able to write z_t as a function solely of the ε_t in equation (A10). In that case, one could then write ε_{t+4} as an infinite order distributed lag of w_{t+4} and v_{t+4} , which would provide the desired interpretation of ε_{t+4} . However, in light of equation (A8), this does not seem to be possible.

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